



Visualization

CH09: Factor Analysis

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Introduction

Motivation: Understanding Latent Structure

- ▶ Many psychological, social, or marketing measurements are inherently latent.
- ▶ Factor analysis identifies underlying variables (factors) that explain the pattern of correlations within a set of observed variables.
- ▶ We consider a consumer survey assessing satisfaction with a product.

Example: Product Satisfaction Survey

Observed variables X_1 to X_8 :

1. X_1 : The price of the product is reasonable.
2. X_2 : The quality of the product is excellent.
3. X_3 : The product meets my expectations.
4. X_4 : Customer service is satisfactory.
5. X_5 : Delivery is prompt.
6. X_6 : The return process is easy.
7. X_7 : The brand image is positive.
8. X_8 : The product is easy to use.

Goal of Factor Analysis

- ▶ Identify latent factors (e.g., “Product Quality”, “Service Experience”, “Brand Perception”) that account for the correlations among these items.
- ▶ Each observed variable is modeled as a linear combination of common factors plus a unique factor.
- ▶ Useful for dimension reduction and interpretation of survey constructs.
 - ▶ X_2, X_3, X_7 : Related to **Product Quality Factors**
 - ▶ X_4, X_5, X_6 : Related to **Service Factors**
 - ▶ X_1, X_7 : Related to **Price and Brand**

Inter-item Score Correlations

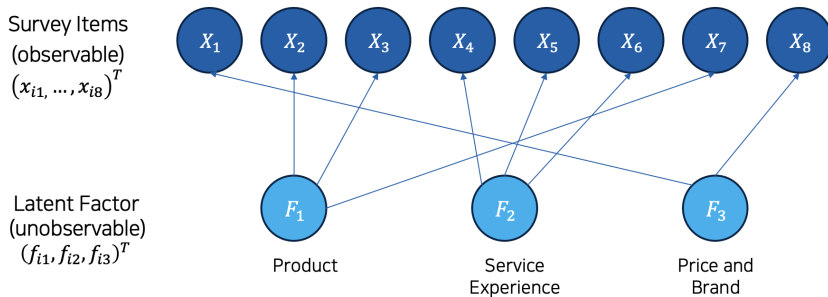


Figure: Visualization of the Factor model

Factor Models

Inter-item Score Correlations

- ▶ **Score Standardization:** $\mathbf{x}_i - \bar{\mathbf{x}}$
 - ▶ For convenience, we denote $\mathbf{x}_i - \bar{\mathbf{x}}$ as \mathbf{x}_i , assuming the mean of the scores is 0.
- ▶ Let \mathbf{x}_i be an 8-dimensional multivariate variable, with components x_{ik} for $k = 1, \dots, 8$ and $i = 1, \dots, n$.
- ▶ $\mathbf{X} \in \mathbb{R}^{n \times p}$: (observed) data matrix where the row i of \mathbf{X} is \mathbf{x}_i^\top .
- ▶ $\mathbf{F} \in \mathbb{R}^{n \times k}$: (latent) factor matrix where the row i of \mathbf{F} is $\mathbf{f}_i^\top = (f_{i1}, f_{i2}, f_{i3})$
- ▶ $\mathbf{\Lambda} \in \mathbb{R}^{p \times k}$: loading matrix where $(\mathbf{\Lambda})_{ij}$ denotes a weight from the factor j to the observed variable i . In Figure the weight denotes the direct link from the factor to the variable (common across the individuals)

Factor Model Representation

$$\mathbf{X} = \mathbf{F}\mathbf{\Lambda}^\top + \boldsymbol{\epsilon}$$

- ▶ $\mathbf{X} \in \mathbb{R}^{n \times p}$: p -dimensional vector of observed variables ($p = 8$ here)
- ▶ $\mathbf{F} \in \mathbb{R}^{n \times k}$: k -dimensional vector of latent factors ($k < p$)
- ▶ $\mathbf{\Lambda} \in \mathbb{R}^{p \times k}$: $p \times k$ factor loading matrix
- ▶ $\boldsymbol{\epsilon} \in \mathbb{R}^{n \times p}$: error matrix (ϵ_i^\top denotes the row i of $\boldsymbol{\epsilon}$.)

Factor Model: Covariance-Based Derivation

Factor model:

$$\mathbf{x}_i = \mathbf{\Lambda} \mathbf{f}_i + \epsilon_i$$

- ▶ $\mathbf{x}_i \in \mathbb{R}^p$: observed variables
- ▶ $\mathbf{f}_i \in \mathbb{R}^k$: common factors
- ▶ $\epsilon_i \in \mathbb{R}^p$: unique factors

Factor Model: Covariance-Based Derivation

Assumptions:

- ▶ $\mathbb{E}[\mathbf{f}_i] = \mathbf{0}$, $\mathbb{E}[\epsilon_i] = 0$
- ▶ $\mathbb{E}[\mathbf{f}_i \mathbf{f}_i^\top] = \mathbf{I}_k$ (factors are standardized)
- ▶ $\mathbb{E}[\epsilon_i \epsilon_i^\top] = \Psi$ (diagonal matrix)
- ▶ $\mathbb{E}[\mathbf{f}_i \epsilon_i^\top] = \mathbf{0}$ (independence)

Covariance structure:

$$\Sigma = \mathbb{E}[\mathbf{x}_i \mathbf{x}_i^\top] = \Lambda \mathbb{E}[\mathbf{f}_i \mathbf{f}_i^\top] \Lambda^\top + \mathbb{E}[\epsilon_i \epsilon_i^\top] = \Lambda \Lambda^\top + \Psi$$

- ▶ $\Sigma \in \mathbb{R}^{p \times p}$: covariance matrix of observed variables

Estimation of Factor Models: Factor Loadings

Estimation of Factor Loadings Λ

Goal: Given the sample covariance matrix $\mathbf{S} \approx \mathbf{\Sigma}$, estimate

$$\mathbf{\Sigma} = \mathbf{\Lambda}\mathbf{\Lambda}^\top + \mathbf{\Psi}$$

Approaches:

▶ **Principal Factor Method (PFA):**

- ▶ Replace $\mathbf{\Psi}$ with initial estimates (e.g., communality), then perform eigen decomposition on $\mathbf{S} - \mathbf{\Psi}$
- ▶ Retain top k eigenvalues/vectors to estimate $\mathbf{\Lambda}$

▶ **Maximum Likelihood Estimation (MLE):**

- ▶ Assume multivariate normality: $\mathbf{x}_i \sim \mathcal{N}_p(\mathbf{0}, \mathbf{\Sigma})$
- ▶ Maximize log-likelihood:

$$\ell(\mathbf{\Lambda}, \mathbf{\Psi}) = -\frac{n}{2} (\log |\mathbf{\Sigma}| + \text{tr}(\mathbf{\Sigma}^{-1}\mathbf{S}))$$

- ▶ Numerical optimization is required

Principal Factor Analysis (PFA)

Step-by-step estimation:

1. Compute the sample covariance matrix \mathbf{S} (estimate of $\mathbf{\Sigma}$)
2. Estimate initial uniqueness: $\mathbf{\Psi}_0 = \text{diag}(\psi_1, \dots, \psi_p)$ (e.g., $\psi_j = s_{jj} - h_j^2$)
3. Define common variance matrix: $\mathbf{S}_c = \mathbf{S} - \mathbf{\Psi}_0$ (estimate of $\mathbf{\Lambda}\mathbf{\Lambda}^\top$)
4. Eigen-decomposition: $\mathbf{S}_c = \mathbf{V}\mathbf{D}\mathbf{V}^\top$
5. Retain top k components:

$$\mathbf{\Lambda} = \mathbf{V}_k \mathbf{D}_k^{1/2}$$

Note: Iterate if desired to update $\mathbf{\Psi}$ using residuals.

MLE Optimization for Factor Analysis (1/2)

Challenge: No closed-form solution for

$$\ell(\mathbf{\Lambda}, \mathbf{\Psi}) = -\frac{n}{2} (\log |\mathbf{\Sigma}| + \text{tr}(\mathbf{\Sigma}^{-1}\mathbf{S}))$$

Approaches:

- ▶ **EM Algorithm**

- ▶ Treat latent factors \mathbf{f}_i as missing data
- ▶ Iteratively update expected sufficient statistics (E-step) and parameter estimates (M-step)
- ▶ Guarantees non-decreasing likelihood

- ▶ **Direct Numerical Optimization**

- ▶ Maximize the likelihood directly over $\mathbf{\Lambda}$ and $\mathbf{\Psi}$
- ▶ Use algorithms such as Newton-Raphson, Fisher scoring, or BFGS

Gradient of the Log-Likelihood (w.r.t. Λ)

Log-likelihood function:

$$\ell(\Lambda, \Psi) = -\frac{n}{2} (\log |\Sigma| + \text{tr}(\Sigma^{-1}S)) \quad \text{with } \Sigma = \Lambda\Lambda^\top + \Psi$$

Gradient with respect to Λ :

$$\frac{\partial \ell}{\partial \Lambda} = -\frac{n}{2} \left(\frac{\partial}{\partial \Lambda} \log |\Sigma| + \frac{\partial}{\partial \Lambda} \text{tr}(\Sigma^{-1}S) \right)$$

Using matrix calculus:

$$\frac{\partial \ell}{\partial \Lambda} = -n (\Sigma^{-1}S\Sigma^{-1} - \Sigma^{-1}) \Lambda$$

Factor Rotation: Motivation

- ▶ Factor loadings $\mathbf{\Lambda}$ are not unique.
- ▶ Any rotation \mathbf{T} of $\mathbf{\Lambda}$ preserves the model:

$$\mathbf{\Lambda}^* = \mathbf{\Lambda}\mathbf{T}, \quad \text{with } \mathbf{T}^\top \mathbf{T} = \mathbf{I}$$

- ▶ Goal: Simplify interpretation by achieving a structure where each variable loads highly on only one factor.

Example:

- ▶ Without rotation: mixed loadings across all factors
- ▶ With rotation: clearer factor-variable associations

Types of Rotation

Orthogonal Rotation (e.g., Varimax):

- ▶ $\Lambda^* = \Lambda \mathbf{T}$
- ▶ $\mathbf{T}^\top \mathbf{T} = \mathbf{I}$
- ▶ Factors remain uncorrelated

Oblique Rotation (e.g., Promax, Oblimin):

- ▶ $\mathbf{T}^\top \mathbf{T} \neq \mathbf{I}$
- ▶ Factor correlation matrix: $\Phi = \mathbf{T}^\top \mathbf{T}$
- ▶ Allows for correlated latent factors

Identifiability under $\Lambda^\top \Lambda = \mathbf{D}$

Factor model:

$$\mathbf{X} = \Lambda \mathbf{f} + \mathbf{e}$$

Assumptions:

- ▶ $\text{Cov}(\mathbf{f}) = \mathbf{I}_k$, $\text{Cov}(\mathbf{e}) = \sigma^2 \mathbf{I}_p$
- ▶ $\text{Cov}(\mathbf{f}, \mathbf{e}) = \mathbf{0}$
- ▶ $\Lambda^\top \Lambda = \mathbf{D}$, diagonal

Implication:

- ▶ This constraint eliminates orthogonal indeterminacy
- ▶ Λ is **identifiable up to sign changes**

Estimation of Factor Models: Factor Scores

Definition of Factor Scores

Factor score: An estimate of the latent factor \mathbf{f}_i for each observation \mathbf{x}_i , based on the model:

$$\mathbf{x}_i = \mathbf{\Lambda} \mathbf{f}_i + \epsilon_i$$

- ▶ $\mathbf{\Lambda} \in \mathbb{R}^{p \times k}$: factor loading matrix
- ▶ $\mathbf{f}_i \sim \mathcal{N}(\mathbf{0}, \mathbf{I}_k)$: latent factors
- ▶ $\epsilon_i \sim \mathcal{N}(\mathbf{0}, \mathbf{\Psi})$: unique factors (diagonal covariance)

Goal: Estimate $\hat{\mathbf{f}}_i \approx \mathbb{E}[\mathbf{f}_i \mid \mathbf{x}_i]$

Derivation: Conditional Expectation

Joint distribution of \mathbf{x}_i and \mathbf{f}_i :

$$\begin{bmatrix} \mathbf{x}_i \\ \mathbf{f}_i \end{bmatrix} \sim \mathcal{N} \left(\begin{bmatrix} \mathbf{0} \\ \mathbf{0} \end{bmatrix}, \begin{bmatrix} \mathbf{\Sigma} & \mathbf{\Lambda} \\ \mathbf{\Lambda}^\top & \mathbf{I}_k \end{bmatrix} \right), \quad \text{where } \mathbf{\Sigma} = \mathbf{\Lambda}\mathbf{\Lambda}^\top + \mathbf{\Psi}$$

From properties of multivariate normal distributions:

$$\mathbb{E}[\mathbf{f}_i \mid \mathbf{x}_i] = \mathbf{\Lambda}^\top \mathbf{\Sigma}^{-1} \mathbf{x}_i$$

Computation Methods for Factor Scores

1. Regression method (Thomson, 1939):

$$\hat{\mathbf{f}}_i = \mathbf{\Lambda}^\top \mathbf{\Sigma}^{-1} \mathbf{x}_i$$

2. Bartlett's method (Bartlett, 1937):

$$\hat{\mathbf{f}}_i = \left(\mathbf{\Lambda}^\top \mathbf{\Psi}^{-1} \mathbf{\Lambda} \right)^{-1} \mathbf{\Lambda}^\top \mathbf{\Psi}^{-1} \mathbf{x}_i$$

- ▶ Bartlett's estimator minimizes the residual unique variance.
- ▶ Regression scores may be correlated across factors, while Bartlett scores are uncorrelated but scale-dependent.

Visualizing Factor Scores

Explore the distribution of observations in the latent factor space.

- ▶ Each observation i has an estimated factor score vector:

$$\hat{\mathbf{f}}_i = (\hat{f}_{i1}, \hat{f}_{i2}, \dots, \hat{f}_{ik})$$

- ▶ Plot \hat{f}_{i1} vs. \hat{f}_{i2} to visualize patterns:
 - ▶ Group separation
 - ▶ Outlier detection
 - ▶ Interpretation of latent dimensions

Common plots:

- ▶ 2D scatter plot of \hat{f}_{i1} and \hat{f}_{i2}
- ▶ Color by categorical groups or cluster labels
- ▶ Add text labels or convex hulls for clusters